

# Tensor principal component analysis via sum-of-squares proofs

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# principal component analysis (PCA)

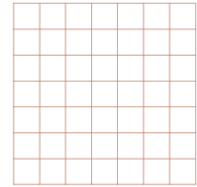
## vanilla PCA

- basic data analysis technique
- given noisy pairwise correlation data  $A \in \mathbb{R}^{n \times n}$ , find direction of maximum empirical variance

maximize  $\langle x, Ax \rangle$  over all unit vectors  $x \in \mathbb{R}^n$

- computationally efficient (take  $x$  to be top eigenvector of  $A$ )

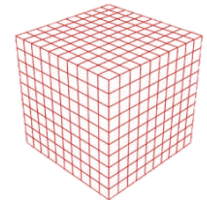
2-wise correlation data  
= matrix



## variants of PCA

- restrict to sparse directions (SPARSE PCA) or exploit higher-order correlation data  $A \in \mathbb{R}^{n \times n \times \dots \times n}$  (TENSOR PCA)
- better statistical properties in important applications; huge body of works
- *but: computationally challenging* (NP-hard in worse case; unclear complexity in stochastic setting)

3-wise correlation data  
= 3-tensor



## tensor principal component analysis

$(k, \tau)$ -stochastic model [Montanari-Richard]

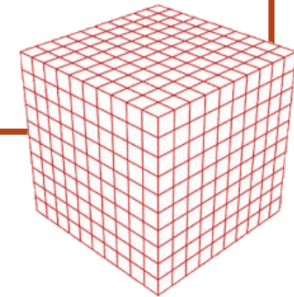
given  $k$ -order tensor  $A$  as below, recover  $v$  (approximately)

$$A = \tau \cdot v^{\otimes k} + Z \in \mathbb{R}^{n^k} \text{ with } Z \sim N(0,1)^{\otimes k}$$

signal-to-noise ratio

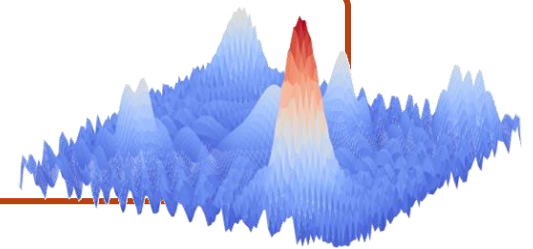
noise: random tensor

signal: rank-1 tensor of unit vector  $v \in \mathbb{R}^n$



maximum likelihood estimation (MLE)

maximize  $\langle A, x^{\otimes k} \rangle$  over all unit vectors  $x \in \mathbb{R}^n$

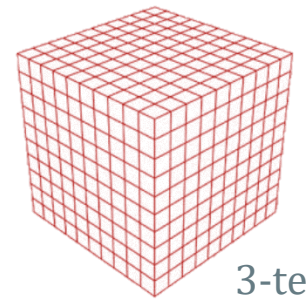


$k = 2$ : computationally efficient (eigenvalue problem; even in worst case)

$k = 3$ : appears to capture difficulty of general  $k$  in stochastic model  
(also NP-hard in worst case, but no bearing on stochastic model)

$$A = \tau \cdot v^{\otimes 3} + Z \in \mathbb{R}^{n^3} \text{ with } Z \sim N(0,1)^{\otimes 3}$$

MLE: maximize  $\langle A, x^{\otimes 3} \rangle$  over all unit vectors  $x \in \mathbb{R}^n$  (\*)



3-tensor

**previous results** [Montanari-Richard=MR]

information-theoretic recovery

(\*) works as long as  $\tau \geq \tilde{O}(n^{1/2})$  (tight)

computational recovery

*MR algorithm:* reshape  $A$  to  $n^2$ -by- $n$  matrix; output top right singular vector

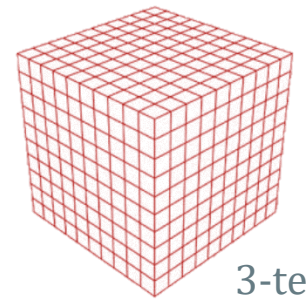
*theoretical guarantee:* algorithm works as long as  $\tau \geq \tilde{O}(n)$

*empirical performance:* algorithm works as long as  $\tau \geq \tilde{O}(n^{3/4})$

**tension:** theoretical analysis of MR *tight* in many ways **but** empirical performance *should be predictive* for mathematical truth (average-case problem & large input sizes)

$$A = \tau \cdot v^{\otimes 3} + Z \in \mathbb{R}^{n^3} \text{ with } Z \sim N(0,1)^{\otimes 3}$$

MLE: maximize  $\langle A, x^{\otimes 3} \rangle$  over all unit vectors  $x \in \mathbb{R}^n$  (\*)



3-tensor

## *this work*

*techniques:* sum-of-squares meta-algorithm & proof system;

***powerful general approach to unsupervised learning***

[Barak-Kelner-S.'12+15, Potechin-Meka-Wigderson'15, Barak-Moitra, Ge-Ma, Ma-Wigderson,...]

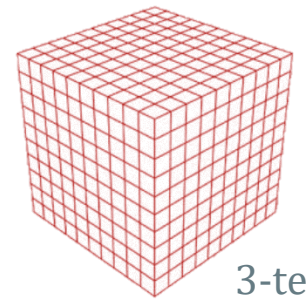
*recovery guarantee:* theoretical analysis matches empirical performance of MR,  
 $\tau \gg n^{3/4}$  — one algorithm very similar to MR

*nearly-linear time:* informed by theoretical analysis; exploit knowledge about eigenvalues to speed up eigenvector computation

*lower bounds:* rule out better recovery guarantees by algorithms based on broad set of techniques (**deg-4 sum-of-squares proof system**)

$$A = \tau \cdot v^{\otimes 3} + Z \in \mathbb{R}^{n^3} \text{ with } Z \sim N(0,1)^{\otimes 3}$$

MLE: maximize  $\langle A, x^{\otimes 3} \rangle$  over all unit vectors  $x \in \mathbb{R}^n$  (\*)



3-tensor

## *relaxation & rounding approach*

*relaxation*: tractable (convex) optimization problem associated with (\*);  
optimal value gives upper bound on optimal value of (\*)

*rounding*: transform solution for relaxation to solution for (\*) with  
approximately same objective value

***failure of this approach***: for  $n^{3/4} \ll \tau \ll n$ ,  
opt. value of MR relaxation (top singular value of  $A$ )  
***is far*** from opt. value of (\*)

*but (empirically)*

opt. solution of MR relaxation  
***is close*** to opt. solution of (\*)

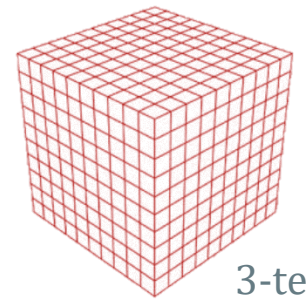
→ ***no rounding analysis possible*** (in the usual sense)

***our explanation*** (for variant of MR relaxation)

***second-order effect*** in opt. value of relaxation drives recovery

$$A = \tau \cdot v^{\otimes 3} + Z \in \mathbb{R}^{n^3} \text{ with } Z \sim N(0,1)^{\otimes 3}$$

MLE: maximize  $\langle A, x^{\otimes 3} \rangle$  over all unit vectors  $x \in \mathbb{R}^n$  (\*)



3-tensor

## sum-of-squares upper bounds

*warm-up:* upper bounds for homogeneous  $n$ -var. deg.-4 polynomial  $p(x)$

consider affine linear subspace  $H_{p(x)}$  of *matrix representations* of  $p(x)$

$$H_{p(x)} \stackrel{\text{def}}{=} \left\{ P \in \mathbb{R}^{n^2 \times n^2} \mid p(x) = \langle x^{\otimes 2}, P x^{\otimes 2} \rangle \right\} \quad \lambda_{\max}(P) = \max_{\|y\|=1} \langle y, P y \rangle$$

then,  $\max_{\|x\|=1} p(x) \leq \lambda_{\max}(P)$  for every  $P \in H_{p(x)}$

→ find *best upper bound*  $\lambda_{\max}(P)$  with  $P \in H_{p(x)}$  (*semidefinite programming*)

## deg- $d$ sum-of-squares upper bounds for general polynomial $p(x)$

find *best upper bound*  $\lambda_{\max}(P)$  with

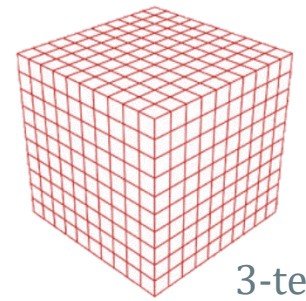
$$P \in \bigcup_{\deg q(x) \leq d-2} H_{p(x)+q(x) \cdot (\|x\|^2-1)}$$

different polynomials but same function as  $p(x)$  on unit sphere

run time  $n^{O(d)}$  (*semidefinite programming*)

$$A = \tau \cdot v^{\otimes 3} + Z \in \mathbb{R}^{n^3} \text{ with } Z \sim N(0,1)^{\otimes 3}$$

MLE: maximize  $\langle A, x^{\otimes 3} \rangle$  over all unit vectors  $x \in \mathbb{R}^n$  (\*)



## efficient upper bounds on random polynomials

*can show:* deg-4 sum-of-squares gives upper bound  $\tau_0 = \tilde{\Theta}(n)^{3/4}$  for random deg-3 polynomial  $z(x) = \langle Z, x^{\otimes 3} \rangle$  over unit sphere

*concretely:*  $z(x) + \tau_0/2 \cdot (\|x\|^4 - \|x\|^2)$  has matrix representation with  $\lambda_{\max}(\cdot) \leq \tau_0$

*approach for recovery:* for  $\tau \gg \tau_0$ , corresponding matrix representation of  $A$  has top eigenvector determined by signal  $v$  (eig.vec. is close to  $v^{\otimes 2}$ )

### where does upper bound for $z(x)$ come from?

reshape  $Z$  to  $n^2$ -by- $n$  matrix so that  $z(x) = \langle Zx, x^{\otimes 2} \rangle$

*tempting but poor Cauchy-Schwarz bound:*  $\langle Zx, x^{\otimes 2} \rangle \leq \sqrt{\|Zx\|^2 \cdot \|x\|^4}$

*tight Cauchy-Schwarz bound:*  $\langle x, Z^T x^{\otimes 2} \rangle \leq \sqrt{\|x\|^2 \cdot \|Z^T x^{\otimes 2}\|^2}$

$Z_i \in \mathbb{R}^{n \times n}$   
 $i$ -th slice of  $Z$

*poor matrix representation for  $\|Z^T x^{\otimes 2}\|^2$ :*  $ZZ^T$  (only rank- $n$ )

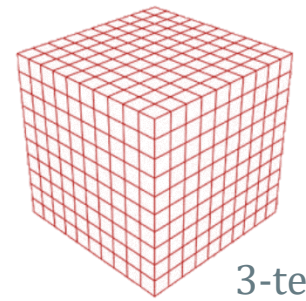
*best matrix representation for  $\sum_i \langle x, Z_i x \rangle^2$ :*  $\sum_i Z_i \otimes Z_i$

use matrix  
Bernstein



$$A = \tau \cdot v^{\otimes 3} + Z \in \mathbb{R}^{n^3} \text{ with } Z \sim N(0,1)^{\otimes 3}$$

MLE: maximize  $\langle A, x^{\otimes 3} \rangle$  over all unit vectors  $x \in \mathbb{R}^n$  (\*)



3-tensor

## conclusion

### sum-of-squares gives new perspective on spectral algorithms

*status quo*: focus on spectrum of single matrix associated with problem;  
e.g., data matrix (matrix problems), Laplacian (graph problems)

*sum-of-squares*: associate hierarchy of increasingly rich families of  
matrices with single problem  $\rightarrow$  *better algorithms*

## research directions

*thank you!*

### faster algorithms via sum-of-squares

*challenge*: size of matrices increases quickly in the hierarchy (albeit poly.)

*upcoming work*: techniques to *significantly compress* matrices in higher  
levels of hierarchy (partial traces) [Hopkins-Schramm-Shi-S'15]

**deg- $O(\log n)$  sum-of-squares enough for  $\tau \geq \tilde{O}(n)^{1/2}$ ?** (info.-theory limit)

